# QG series



QG76-SD-010H-AI-CM

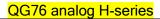
## **Inclination sensor**

2 axis horizontal mounting

Programmable device Output: 4 - 20 mA

Measuring range programmable between ±1° and ±10°

Measuring range Factory defaults: ± 10°







Housing		
Dimensions (indicative)		
Mounting		
Ingress Protection (IEC 60529)		
Relative humidity		
Weight		
Supply voltage		
Polarity protection		
Current consumption		
Operating temperature		
Storage temperature		
Measuring range		
Centering function		
Frequency response (-3dB)		
Accuracy (typ. and/or 2σ)		
Offset error		
Non linearity		
Sensitivity error		
Resolution		
Temperature coefficient		
Max mechanical shock		
Output		
Output load		
Short circuit protection		
Output refresh rate		
Programming options		

General specifications 12388, v20170825
Stainless steel (AISI 316)
70x60x33 mm
Included: 4x M4x30 mm stainless steel (A4) Hexagon socket head screws
IP67
0 - 100%
approx. 700 gram
10 - 30 V dc
Yes
≤ 50 mA ( excluding output signal )
-40 +85 °C
-40 +85 °C
Factory defaults: ± 10°
Yes (12 mA = 0°), range: ±5°
0 - 10 Hz
overall 0,04° typ.
< ± 0,02° typ. (< ± 0,05° max.) after centering
< ± 0,04° typ. (< ± 0,09° max.)
not applicable
0,01°
± 0,005°/K typ.
20.000g
4 - 20 mA
Rload $\leq$ (50*Vs-300) [ $\Omega$ ] (Eg: Vs = 24 V: Rload $\leq$ 900 $\Omega$ )
Yes (max 10 s)
20 ms
by optional QG65-configurator (measuring range, filtering)

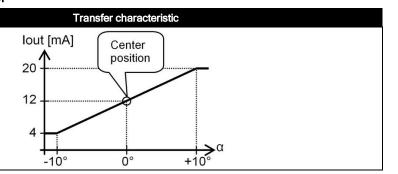
## **QG** series



lout =  $12 + 8*(\alpha/10)$  [mA]

clipping outside measuring range

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Default 0°: horizontal (top upwards), no acceleration applied.

Cross tilt sensitivity error: < (0,12 \* cross tilt angle)2 % typ.

 $\rightarrow$  one axis <10° tilt for max. accuracy

gravity Male

Measurement orientation

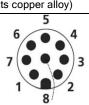
## Connection

Wire / pin coding

## Connectivity (length ±10%)

M12 male 8p connector (stainless steel 1.4404 (316L), contacts copper alloy)

Pin 1:	Output Y	5
Pin 2:	Supply voltage	6
Pin 3:	Programming interface RS232 Rx	
Pin 4:	Programming interface RS232 Tx	7 0 0
Pin 5:	Gnd	
Pin 6:	Centering input	1
Pin 7:	Output X	0
Pin 8:	Not connected	8



# Mechanical dimensions (indicative only) 0 MALE

## Center function

Centering can be done to eliminate mechanical offsets. To execute centering connect center input to ground (>0,5sec) within 1 min. after power up. After centering you have 1 min. left for another centering. Normally the center input should be left unconnected.

As this device is accelerometer-based the sensor is inherent sensitive for accelerations/vibrations. Application specific testing must be carried out to check whether this sensor will fulfil your requirements.