

QG series

SIL2 / PLd Certified sensor

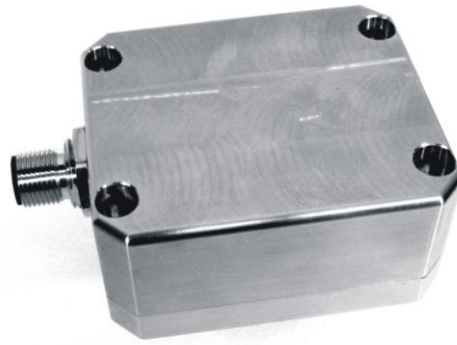
QG76N-SDXYh-030-CANS-C(F)M-2d

Safety inclination sensor
2 axis horizontal mounting

Programmable device
Interface: CANopen Safety

SIL CL 2 (acc. to IEC 62061)
PLd (acc. to EN ISO 13849)

Measuring range
 $\pm 30^\circ$



CANopen
safety easy to use



Housing	Stainless steel (AISI 316)
Dimensions (indicative)	70x60x33 mm
Mounting	Included: 4x M4x30 mm stainless steel (A4) Hexagon socket head screws
Ingress Protection (IEC 60529)	IP67 (IP68 with optional cable gland)
Relative humidity	0 - 100%
Weight	approx. 700 gram
Supply voltage	8 - 60 V dc SELV
Polarity protection	Yes
Current consumption	≤ 25 mA
Operating temperature	-40 .. +85 °C
Storage temperature	-40 .. +85 °C
Measuring range	$\pm 30^\circ$
Centering function	Yes (CANout 0 = 0°), range: $\pm 5^\circ$
Frequency response (-3dB)	0 - 20 Hz
Typ. Accuracy @20°C (2 σ)	overall 0,15° typ.
Offset error	$< \pm 0,05^\circ$ typ. ($< \pm 0,1^\circ$ max.) after centering
Non linearity	$< \pm 0,1^\circ$ typ. ($< \pm 0,2^\circ$ max.)
Sensitivity error	not applicable
Resolution	0.05°
Temperature coefficient	$\pm 0,01^\circ/\text{K}$ typ.
Max mechanical shock	10.000 g
CAN interface (hardware)	According to ISO 11898-1 & ISO 11898-2 (also known as CAN 2.0 A/B)
CANopen application layer and communication profile	CANopen Safety protocol: EN 50325-5, CANopen protocol: EN 50325-4 (CiA 301 v4.0 & 4.2.0) CANopen device profile for inclinometers: CiA 410 version 2.0.0
Baud rate	125 kbit/s (default, range 10/20/50/100/125/250/500/800/1000 kbit/s)
Node Id	01h (default, range: 01h - 3Fh) (01h - 7Fh with adapted COB-ID's)
TPDO1 event time	50 ms (default, range 10-500 ms)
Sync mode (TPDO's), Heartbeat	off (default, range on/off)
Output format	Integer: -3000 to +3000 (SRDO:X=byte 2,1; Y=byte 4,3)
SRDO1 COB-ID1	FFh + 2x node ID (for Node ID=01h: SRDO1 COB-ID1=101h)
SRDO1 COB-ID2	100h + 2x node ID (for Node ID=01h: SRDO1 COB-ID2=102h)
Safeguard cycle time (SCT)	80ms in CAN object dictionary, worst case 100ms
Safety related validation time (SRVT)	20ms
Filtering	Output filter disabled
Reaction on error	Emergency message 080h+Node-ID followed by NMT stop state (no CAN communication)
Boot time	< 1 s
Programming options	by CANopen object dictionary (CAN parameters, filtering)

General specifications v20190501	
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