

QR series

QR40-360HB-VK-5V

Absolute rotary encoder (contactless)

Output

0 - 5 V (ratiometric to 5 V
supply voltage)

Supply voltage

5V dc

Measuring range

360°



General specifications 12646, v20200323

Quadro40: PBT black

40x40x22 mm

Included: 2x M4x25 stainless steel pozidrive pan head screws, self-tapping (PZ DIN7500CZ)

IP66

0 - 95% (non condensing, fully potted)

approx 75 gr (excl. cable)

Stainless steel Ø 6 mm

D-form

Polyamide (glass-filled), Radial force < 1Nm, Axial force < 8N (push & pull)

8 mm

5V dc

No

≤ 50 mA

-25 to 80°C

-25 to 85°C

360°

Yes (2,5 V / 180°)

12 bit over 360° (min. step 0,09°)

±0.5% typ. (@20°C), ±1% typ. (full Temp. range)

± 1% (after centering)

< ± 1,4°

0,26°

< 10 ms

15 rpm

0 - 5 V (ratiometric to 5 V supply voltage)

Yes (T<55°C), Max 10 s (T>55°C)

≥ 20 kΩ

Cable 2 m PVC/PVC Liyy, black Ø 4,6 mm, wires: 4x0,25 mm² Sensor colors (static usage)

Brown	+ Supply voltage
Black	Output
Blue	Gnd
White	Center input

Housing

Dimensions (indicative)

Mounting

Ingress Protection (IEC 60529)

Relative Humidity

Weight

Shaft

Shaft type

Shaft bearing

Shaft length

Supply voltage

Polarity protection

Current consumption

Operating temperature

Storage temperature

Measuring range

Programmable center position

Accuracy

Resolution

Sensitivity error

Offset error

Non linearity

Repeatability

Response time

Max speed

Output signal

Short circuit protection

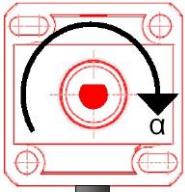
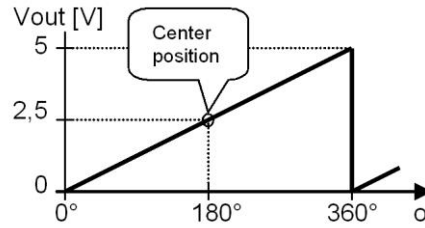
Output load resistor

Connection (length ±10%)

Wire coding

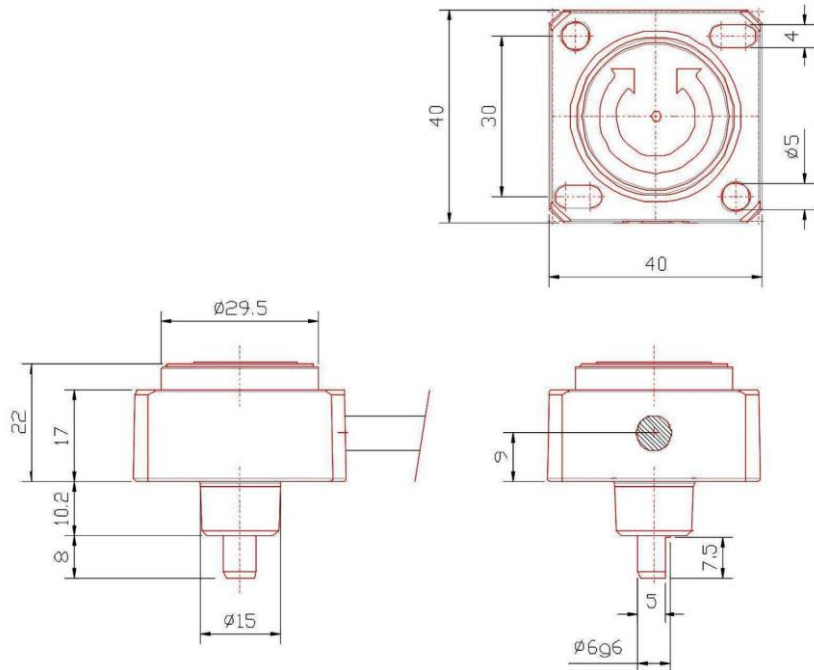
QR40-360HB-VK-5V

Transfer characteristic



Rotation axis: CW

Dimensions (indicative only)



Centering

Centering will store the current angle position as new center position into permanent memory. Centering can only be done in the 1st min. after power up, or within the 1st min. after centering. To perform a centering action the center input should be unconnected during power up, than connect the center input to ground for more than 1/2 sec. to activate centering. Centering is used to correct mechanical offsets.