QG series



QG65N2 CANopen Standard accuracy series

QG65N2-KDXYh-030-CAN-C(F)M-UL

Inclination sensor

2 axis horizontal mounting

Programmable device Interface: CANopen

Parameters programmable by DIS configurator and CANopen object dictionary

Measuring range ± 30°







± 30°
Housing
Dimensions (indicative)
Mounting
Ingress Protection (IEC 60529)
Relative humidity
Weight
Supply voltage
Polarity protection
Current consumption
Operating temperature
Storage temperature
Measuring range
Centering function
Frequency response (-3dB)
Accuracy (overall @20°C)
Offset error
Non linearity
Sensitivity error
Resolution
Temperature coefficient
Max mechanical shock
CAN interface (physical layer)
CANopen application layer and
communication profile Baud rate
Node Id
TPDO Event time
Sync mode
Heartbeat
Programming options
Output format Filtering
Modes of operation
Internal CANbus termination
Boot time
Programming options

General specifications 12824, 12827, v20221011
Reinforced plastic injection molded (Faradex DS, black, EMI shielded by stainless steel fiber in PC)
60x50x27 mm
Included: 4x M5x25 mm zinc plated steel pozidrive pan head screws, self-tapping (PZ DIN7500CZ) Mounting on flat surface only. Screw crosswise with maximum Torque 2.5 Nm
IP67, IP69K (with IP69K mating connector)
0 - 95% (non condensing, housing fully potted)
approx. 110 gram
10 - 32 V dc
Yes
50mA typ. For CFM models (daisy-chained CANbus): max. current internal T-junction: 2.5A
-40 +80 °C
-40 +85 °C
± 30°
Yes (CANout 0 = 0°), range: ±5°
0 - 10 Hz
0,15° typ.
\pm 0,05° typ. (\pm 0,1° 2 σ) after centering
\pm 0,1° typ., \pm 0,15° 2 σ , \pm 0,2° max.
not applicable. Repeatability 0,1°
0,01°
T>0°C: 0.015°/K typ. en T<0°C: 0.03°/K typ.
10,000g (max 0,2ms)
According to ISO 11898-1 & ISO 11898-2 (CAN 2.0 A/B), Short circuit protected
CANopen, CiA301 V4.2.0 & EN 50325-4 + Device Profile CiA410 DSP 2.0.0 for inclinometers
250 kbit/s (default, range 10/20/50/100/125/250/500/800/1000 kbit/s 01h (range: 01h - 7Fh) For Node ID=01h: TPDO1: 181h, TPDO2: 281h TPDO1: 10 - 500 ms (default: 100 ms) On/off (default: off) On/off (default: on, 2s) Baudrate, Node Id, Event time, Sync mode, Heartbeat, Output format, CANbus termination, filtering Integer: -3000 to +3000 (PDO1:X=byte 2,1;Y=byte 4,3) Bessel LPF 10Hz on, TPDO averaging off, Output filter off Event mode, Sync-mode. Default: auto-startup Event mode 120 Ohm on/off (default: off)
< 0.5 s

by optional DIS Configurator and CANopen object dictionary (CAN parameters, filtering)

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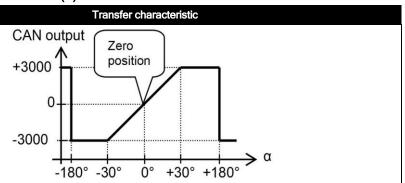


CANoutput = 100*α

Clipping outside measuring range

Zeroing can be done to eliminate mounting offsets.

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Default 0°: horizontal (label upwards), no acceleration applied. To eliminate mounting offsets the sensor can be zero-ed within ±5° tilt (by the CAN object dictionary)

Cross tilt sensitivity error: < (0,12 * cross tilt angle)2 % typ.

→ one axis <10° tilt for max.</p> accuracy

Measurement orientation

Connectivity (cable length ±10%)

Male only or Male & Female (internal T-junction) M12 connector (5 pins, A-coding) (CiA303 V1.8.0) (Brass Nickel coated, contacts copper alloy)

A CANbus always has to be terminated properly according to customers bus topology and general CAN rules.

The sensor has an on-board internal 120 Ohm CANbus termination resistor that can be switched on by the CANopen dictionary (default: off).

Alternatively an external M12 termination resistor can be connected when using a Male & Female (internal T-junction) model.

External M12 termination resistors and T-connectors are available as accessoire see DIS website.

Pin 1: Shield

Pin 2:

Pin 3:

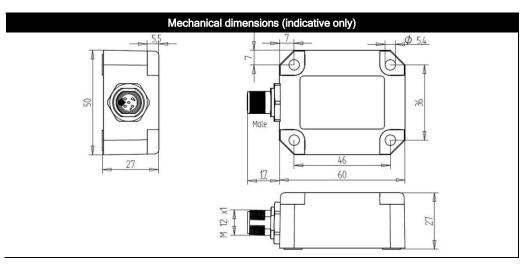
Pin 4:

Pin 5:



Wire / pin coding

Connection



QG series



E4ready, UL, CAN-manual, EDS-file, Ordering codes

Before using this device, please read this datasheet, the Manual and the Declaration of Conformity carefully (download from dis-sensors.com)

This product is E4ready and meets Automotive EMC requirements

Connect this sensor only to an approved CAN controller which must have a grounded shield. Alternativelly, connect the sensor housing to a grounded shield. All mentioned EMC standards that are met (see Declaration of Conformity) have been done with the housing connected to a grounded shield.

QG series sensors are intended to measure inclination/acceleration/tilt. Flawless function (acc. spec.) is ensured only when used within specifications. This device is not a safety component acc. to EU Machine Directive (ISO13849). For full redundancy two devices can be used. Modifications or non-approved use will result in loss of warranty and void any claims against the manufacturer.

UL & c-UL listed product (File number E312057, UL508 standards UL60947-5-2 & CSA-C22,2 No. 14) Product Identity / Category Code Number (CCN): Industrial Control Equipment / NRKH & NRKH7 Enclosure rating: type 1, Ambient temperature: max 80 °C (see also datasheet, lowest value applies) Electrical ratings: Intended to be used with a Class 2 power source in accordance with UL1310, max. input Voltage 32V dc (see also datasheet, lowest value applies), max. current 200mA Accessory Cable Assembly: Any UL-listed (CYJV/7) mating connector with mechanical locking, wire thickness of at least 30 AWG (0,05 mm²), recommended ≤23 AWG (≥0,25 mm²)

Optional: for accurate mounting two factory mounted positioning pins can be mounted (Ø4mm) replacing 2x M5x25 mm.

As this device is accelerometer-based the sensor is inherent sensitive for accelerations/vibrations.

A CAN-manual can be downloaded from www-dis-sensors.com (type I) EDS-file (CiA306 V1.3.0) can be downloaded from www.dis-sensors.com (type I)

Ordering codes:

M12 Male: QG65N2-KDXYh-030-CAN-CM-UL, 12824

M12 Male & Female: QG65N2-KDXYh-030-CAN-CFM-UL, 12827