QG series



QG65N2 SAE J1939 High accuracy series

QG65N2-KIXv-360H-CANJ-C(F)M-UL

Inclination sensor

1 axis vertical mounting

Programmable device Interface: CAN SAE J1939

Parameters programmable by J1939

Measuring range ±180°





Dimensions (indicative) Mounting Ingress Protection (IEC 60529) Relative humidity Weight upply voltage Polarity protection Current consumption perating temperature torage temperature easuring range entering function requency response (-3dB) ccuracy (overall @20°C) Offset error Non linearity Sensitivity error Resolution Temperature coefficient ax mechanical shock AN interface SAE J1939 Baud rate Default address PGN PGN cycle time Priority Output format Internal CANbus termination poot time	
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Offset error Non linearity Sensitivity error Resolution Temperature coefficient ax mechanical shock AN interface SAE J1939 Baud rate Default address PGN PGN cycle time Priority Output format Internal CANbus termination boot time	Frequency response (-3dB)
Non linearity Sensitivity error Resolution Temperature coefficient ax mechanical shock AN interface SAE J1939 Baud rate Default address PGN PGN cycle time Priority Output format Internal CANbus termination poot time	Accuracy (overall @20°C)
Sensitivity error Resolution Temperature coefficient ax mechanical shock AN interface SAE J1939 Baud rate Default address PGN PGN cycle time Priority Output format Internal CANbus termination boot time	Offset error
Resolution Temperature coefficient ax mechanical shock AN interface SAE J1939 Baud rate Default address PGN PGN cycle time Priority Output format Internal CANbus termination	Non linearity
Temperature coefficient ax mechanical shock AN interface SAE J1939 Baud rate Default address PGN PGN cycle time Priority Output format Internal CANbus termination bot time	Sensitivity error
ax mechanical shock AN interface SAE J1939 Baud rate Default address PGN PGN cycle time Priority Output format Internal CANbus termination boot time	Resolution
SAE J1939 Baud rate Default address PGN PGN cycle time Priority Output format Internal CANbus termination oot time	Temperature coefficient
SAE J1939 Baud rate Default address PGN PGN cycle time Priority Output format Internal CANbus termination oot time	Max mechanical shock
Baud rate Default address PGN PGN cycle time Priority Output format Internal CANbus termination	CAN interface
Default address PGN PGN cycle time Priority Output format Internal CANbus termination oot time	SAE J1939
oot time	Default address PGN PGN cycle time Priority Output format
rogramming options	Boot time
	Programming options

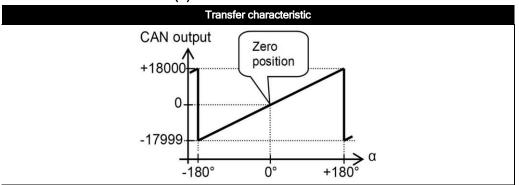
	General specifications 14109, 14112, v20221011
Reinforced p	plastic injection molded (Faradex DS, black, EMI shielded by stainless steel fiber in PC)
	60x50x27 mm
	M5x25 mm zinc plated steel pozidrive pan head screws, self-tapping (PZ DIN7500CZ) ounting on flat surface only. Screw crosswise with maximum Torque 2.5 Nm
	IP67, IP69K (with IP69K mating connector)
	0 - 95% (non condensing, housing fully potted)
	approx. 110 gram
	10 - 32 V dc
	Yes
50mA typ	p. For CFM models (daisy-chained CANbus): max. current internal T-junction: 2.5A
	-40 +80 °C
	-40 +85 °C
	±180°
	Yes (CANout 0 = 0°), range: 360°
	0 - 10 Hz
	0,07° typ.
	\pm 0,01° typ. (\pm 0,02° 2 σ) after centering
	$\pm 0.06^{\circ}$ typ., $\pm 0.1^{\circ} 2\sigma$, $\pm 0.15^{\circ}$ max.
	not applicable. Repeatability 0,05°
	0,01°
	± 0.003°/K typ., ± 0.005°/K (2σ)
	10,000g (max 0,2ms)
Acc	cording to ISO 11898-1 & ISO 11898-2 (CAN 2.0 A/B), Short circuit protected
	SAE J1939
	250 kbit/s (range 250/500kbit/s) 80h = 128dec Inclination: FF00h = 65280dec 100ms 3 (default)
	Integer: -17999 to +18000 (X=byte 1,0; Y=byte 3,2) 120 Ohm on/off (default: off) < 0.5 s
	J1939 parameters: baud rate, device address PGN, cycle time, priority. Sensor functions: internal CANbus termination

QG series



J1939 output = $100*\alpha$

QG65N2-KIXv-360H-CANJ-C(F)M-UL



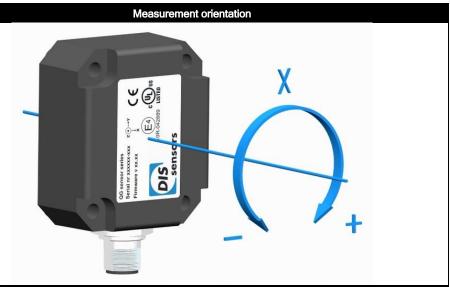
Rotation in vertical plane.

Lateral tilt sensitivity error: < ± 0,03°/° lateral tilt (typ.) Max. lateral tilt: 45°

Drawn in the default 0° sensor orientation position Zeroing can be done to change the sensor orientation at 0° point

Connection

Wire / pin coding



Connectivity (cable length ±10%)

Male only or Male & Female (internal T-junction) M12 connector (5 pins, A-coding) (CiA303 V1.8.0) (Brass Nickel coated, contacts copper alloy)

A CANbus always has to be terminated properly according to customers bus topology and general CAN rules.

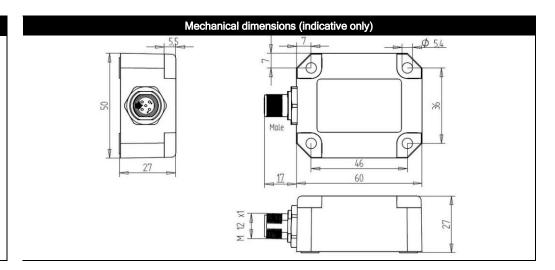
The sensor has an on-board internal 120 Ohm CANbus termination resistor that can be switched on by the CANopen dictionary (default: off).

Alternatively an external M12 termination resistor can be connected when using a Male & Female (internal T-junction) model.

External M12 termination resistors and T-connectors are available as accessoire, see DIS website. Ρ

Pin 1:	Shield	4 3	3 4
Pin 2:	Vcc	(5)	(5)
Pin 3:	Gnd & CAN_GND		
Pin 4:	CAN_H	1 2	2 1
Pin 5:	CAN_L	Male	Female





E4ready, UL, J1939-manual, Ordering codes

Before using this device, please read this datasheet, the Manual and the Declaration of Conformity carefully (download from dis-sensors.com)

This product is E4ready and meets Automotive EMC requirements

Connect this sensor only to an approved CAN controller which must have a grounded shield. Alternativelly, connect the sensor housing to a grounded shield. All mentioned EMC standards that are met (see Declaration of Conformity) have been done with the housing connected to a grounded shield.

QG series sensors are intended to measure inclination/acceleration/tilt. Flawless function (acc. spec.) is ensured only when used within specifications. This device is not a safety component acc. to EU Machine Directive (ISO13849). For full redundancy two devices can be used. Modifications or non-approved use will result in loss of warranty and void any claims against the manufacturer.

UL & c-UL listed product (File number E312057, UL508 standards UL60947-5-2 & CSA-C22,2 No. 14) Product Identity / Category Code Number (CCN): Industrial Control Equipment / NRKH & NRKH7 Enclosure rating: type 1, Ambient temperature: max 80 °C (see also datasheet, lowest value applies) Electrical ratings: Intended to be used with a Class 2 power source in accordance with UL1310, max. input Voltage 32V dc (see also datasheet, lowest value applies), max. current 200mA Accessory Cable Assembly: Any UL-listed (CYJV/7) mating connector with mechanical locking, wire thickness of at least 30 AWG (0,05 mm²), recommended ≤23 AWG (≥0,25 mm²)

Optional: for accurate mounting two factory mounted positioning pins can be mounted (Ø4mm) replacing 2x M5x25 mm.

As this device is accelerometer-based the sensor is inherent sensitive for accelerations/vibrations. Application specific testing must be carried out to check whether this sensor will fulfil customers requirements.

A 1939 manual can be downloaded from the website (Type JB)

Ordering codes:

QG65N2-KDXYh-360H-CANJ-CM-UL: 14109 QG65N2-KDXYh-360H-CANJ-CFM-UL: 14112