QG series



QG76D-SIXv-360H-CAN-C(F)M-UL

Dynamic Inclination sensor

1 axis vertical mounting

Programmable device Interface: CANopen

Parameters programmable by DIS configurator and CANopen object dictionary

Measuring range ±180°

QG76D CAN High accuracy series





Housing			
Dimensions (indicative)			
Mounting			
Ingress Protection (IEC 60529)			
Relative humidity			
Weight			
Supply voltage			
Polarity protection			
Current consumption			
Operating temperature			
Storage temperature			
Measuring range			
Centering function			
Frequency response (-3dB)			
Accuracy (overall @20°C)			
Offset error			
Non linearity			
Sensitivity error			
Resolution			
Temperature coefficient			
Max mechanical shock			
CAN interface (physical layer)			
CANopen application layer and			
communication profile Baud rate			
Node Id			
TPDO			
Event time			
Sync mode Heartbeat			
Programming options			
Output format			
Application profiles			
Modes of operation			
Internal CANbus termination			
Boot time			

Programming options

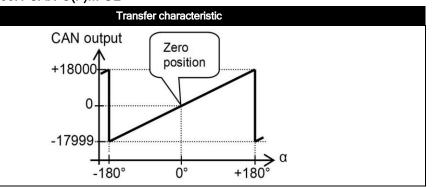
General specifications 12801, 12802, v20230412	
Stainless steel (AISI 316)	
70x60x33 mm	
Not Included: 4x M4x30 mm stainless steel (A4) Hexagon socket head screws	5
IP67, IP69K (with IP69K mating connector), (IP68 with optional cable gland)	
0 - 95% (non condensing, housing fully potted)	
approx. 700 gram	
10 - 32 V dc	
Yes	
50mA typ. For CFM models (daisy-chained CANbus): max. current internal T-junction	n: 2.5A
-40 +80 °C	
-40 +85 °C	
±180°	
Yes (CANout 0 = 0°), range: 360°	
0 - 100 Hz, Max angle rate 500°/s	
0,07° typ. (static), 0,5° typ. (dynamic)	
± 0,01° typ. (± 0,02° 2σ) after centering	
Static: \pm 0.06° typ., \pm 0,1° 2 σ , \pm 0.15° max, Dynamic: \pm 0,5° typ. (*) (**)	
not applicable. Repeatability 0,05°	
0,01°	
$\pm 0.003^{\circ}$ /K typ., $\pm 0.005^{\circ}$ /K (2 σ)	
10,000g (max 0,2ms)	
According to ISO 11898-1 & ISO 11898-2 (CAN 2.0 A/B), Short circuit protecte	ed
CANopen, CiA301 V4.2.0 & EN 50325-4 + Device Profile CiA410 DSP 2.0.0 for inclin	nometers
250 kbit/s (default, range 10/20/50/100/125/250/500/800/1000 kbit/s 01h (range: 01h - 7Fh) For Node ID=01h: TPDO1: 181h, TPDO2: 281h TPDO1: 10 - 500 ms (default: 100 ms) On/off (default: off) On/off (default: on, 2s) Baudrate, Node Id, Event time, Sync mode, Heartbeat, Output format, CANbus termination Integer: -17999 to +18000 (PDO1:byte 2,1)	on, filtering
0/1/2/3 (factory default: profile 1) Event mode, Sync-mode. Default: auto-startup Event mode 120 Ohm on/off (default: off)	
< 0.5 s by Optional DIS Configurator set CAN	
and CANopen object dictionary (CAN parameters, application profiles, filtering	J)

QG series



CANoutput = 100*α

QG76D-SIXv-360H-CAN-C(F)M-UL



Rotation in vertical plane.

Lateral tilt sensitivity error: $< \pm 0.03^{\circ}/^{\circ}$ lateral tilt (typ.) Max. lateral tilt: 45°

Drawn in the default 0° sensor orientation position Zeroing can be done to change the sensor orientation at 0° point

Connection

Wire / pin coding

Measurement orientation

Connectivity (cable length ±10%)

Male only or Male & Female (internal T-junction) M12 connector (5 pins, A-coding) (CiA303 V1.8.0) (stainless steel 1.4404 (316L), contacts copper alloy)

A CANbus always has to be terminated properly according to customers bus topology and general CAN rules.

The sensor has an on-board internal 120 Ohm CANbus termination resistor that can be switched on by

the CANopen dictionary (default: off).

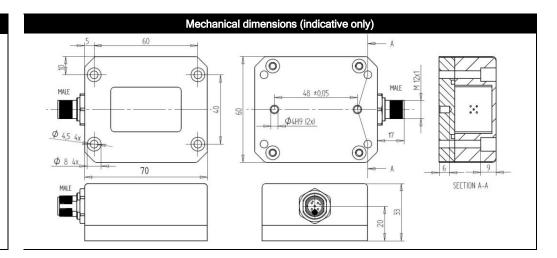
Alternatively an external M12 termination resistor can be connected when using a Male & Female (internal T-junction) model.

External M12 termination resistors and T-connectors are available as accessoire, see DIS website.

Pin 1: Shield 4 3 3 4 4

Pin 1:	Shield	4 5 3	3 4
Pin 2:	Vcc	(5)	3 5 6 4
Pin 3:	Gnd & CAN_GND		
Pin 4:	CAN_H	1 2	2 1
Pin 5:	CAN_L	Male	Female





E4ready, UL, CAN-manual, EDS-file, Ordering codes

Before using this device, please read this datasheet, the Manual and the Declaration of Conformity carefully (download from dis-sensors.com)

This product is E4ready and meets Automotive EMC requirements

QG series sensors are intended to measure inclination/acceleration/tilt. Flawless function (acc. spec.) is ensured only when used within specifications. This device is not a safety component acc. to EU Machine Directive (ISO13849). For full redundancy two devices can be used. Modifications or non-approved use will result in loss of warranty and void any claims against the manufacturer.

UL & c-UL listed product (File number E312057, UL508 standards UL60947-5-2 & CSA-C22,2 No. 14) Product Identity / Category Code Number (CCN): Industrial Control Equipment / NRKH & NRKH7 Enclosure rating: type 1, Ambient temperature: max 80 °C (see also datasheet, lowest value applies) Electrical ratings: Intended to be used with a Class 2 power source in accordance with UL1310, max. input Voltage 32V dc (see also datasheet, lowest value applies), max. current 200mA Accessory Cable Assembly: Any UL-listed (CYJV/7) mating connector with mechanical locking, wire thickness of at least 30 AWG (0,05 mm²), recommended ≤23 AWG (≥0,25 mm²)

(*) Accuracy within spec : approx.. 30sec after boot-up.

(**) Dynamic accuracy figures based on Robot tests, robot performing actions representative for general mobile machine movements

As this device is accelerometer-based the sensor is inherent sensitive for accelerations/vibrations. The majority of these dynamic effects will be eliminated by the on-board gyroscope.

The on-board gyroscope and Kalmann filtering are special designed to prevent the inclinometer to become significant inaccurate in dynamic situations. The sensor has pre-programmed Kalmann algorithms ('Application profiles') that can be selected via the CANbus

Application specific testing must be carried out to check which compensation algorithm fits the application best, and whether this sensor will fulfil customers requirements.

A CAN-manual and EDS-file (CiA306 V1.3.0) can be downloaded from the website (Type H)

Ordering codes:

M12 Male: QG76D-SIXv-360H-CAN-CM-UL, 12801

M12 Male & Female: QG76D-SIXv-360H-CAN-CFM-UL, 12802