

QG65D CANopen High accuracy series

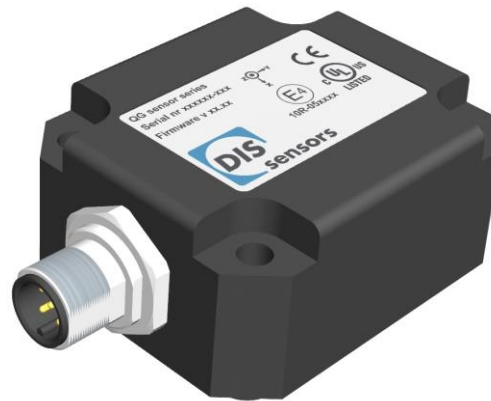
QG65D-KIXv-360H-CAN-C(F)M-UL

Dynamic Inclination sensor 1 axis vertical mounting

Programmable device
Interface: CANopen

Parameters programmable
by DIS configurator and
CANopen object dictionary

Measuring range
 $\pm 180^\circ$



General specifications 12609, 12610, v20210614

| | |
|---|--|
| Housing | Reinforced plastic injection molded (Faradex DS, black, EMI shielded by stainless steel fiber in PC) |
| Dimensions (indicative) | 60x50x27 mm |
| Mounting | Included: 4x M5x25 mm zinc plated steel pozidrive pan head screws, self-tapping (PZ DIN7500CZ) (optional: Factory mounted 2x Ø4mm positioning pins replacing 2x M5x25 mm) |
| Ingress Protection (IEC 60529) | IP67, IP69K (with IP69K mating connector) |
| Relative humidity | 0 - 95% (non condensing, housing fully potted) |
| Weight | approx. 110 gram |
| Supply voltage | 10 - 32 V dc |
| Polarity protection | Yes |
| Current consumption | 50mA typ. For CFM models (daisy-chained CANbus): max. current internal T-junction: 2.5A |
| Operating temperature | -40 .. +80 °C |
| Storage temperature | -40 .. +85 °C |
| Measuring range | $\pm 180^\circ$ |
| Centering function | Yes (CANout 0 = 0°), range: 360° |
| Frequency response (-3dB) | 0 - 100 Hz, Max angle rate 500°/s |
| Accuracy (overall @20°C) | 0,07° typ. (static), 0,5° typ. (dynamic) |
| Offset error | $\pm 0,01^\circ$ typ. ($\pm 0,02^\circ$ 2 σ) after centering |
| Non linearity | Static: $\pm 0.06^\circ$ typ., $\pm 0,1^\circ$ 2 σ , $\pm 0.15^\circ$ max, Dynamic: $\pm 0,5^\circ$ typ. (*) (**) |
| Sensitivity error | not applicable. Repeatability 0,05° |
| Resolution | 0,01° |
| Temperature coefficient | $\pm 0.003^\circ/K$ typ., $\pm 0.005^\circ/K$ (2 σ) |
| Max mechanical shock | 10,000g (max 0,2ms) |
| CAN interface (physical layer) | According to ISO 11898-1 & ISO 11898-2 (CAN 2.0 A/B), Short circuit protected |
| CANopen application layer and communication profile | CANopen, CiA301 V4.2.0 & EN 50325-4 + Device Profile CiA410 DSP 2.0.0 for inclinometers |
| Baud rate | 250 kbit/s (default, range 10/20/50/100/125/250/500/800/1000 kbit/s) |
| Node Id | 01h (range: 01h - 7Fh) |
| TPDO | For Node ID=01h: TPDO1: 181h, TPDO2: 281h |
| Event time | TPDO1: 10 - 500 ms (default: 100 ms) |
| Sync mode | On/off (default: off) |
| Heartbeat | On/off (default: on, 2s) |
| Programming options | Baudrate, Node Id, Event time, Sync mode, Heartbeat, Output format, CANbus termination, filtering |
| Output format | Integer: -17999 to +18000 (PDO1:byte 2,1) |
| Application profiles | 0/1/2/3 (factory default: profile 1) |
| Modes of operation | Event mode, Sync-mode. Default: auto-startup Event mode |
| Internal CANbus termination | 120 Ohm on/off (default: off) |
| Boot time | < 0.5 s |
| Programming options | by Optional DIS Configurator set CAN and CANopen object dictionary (CAN parameters, application profiles, filtering) |

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CANoutput = $100 \cdot \alpha$

Zeroing can be done to eliminate mounting offsets.

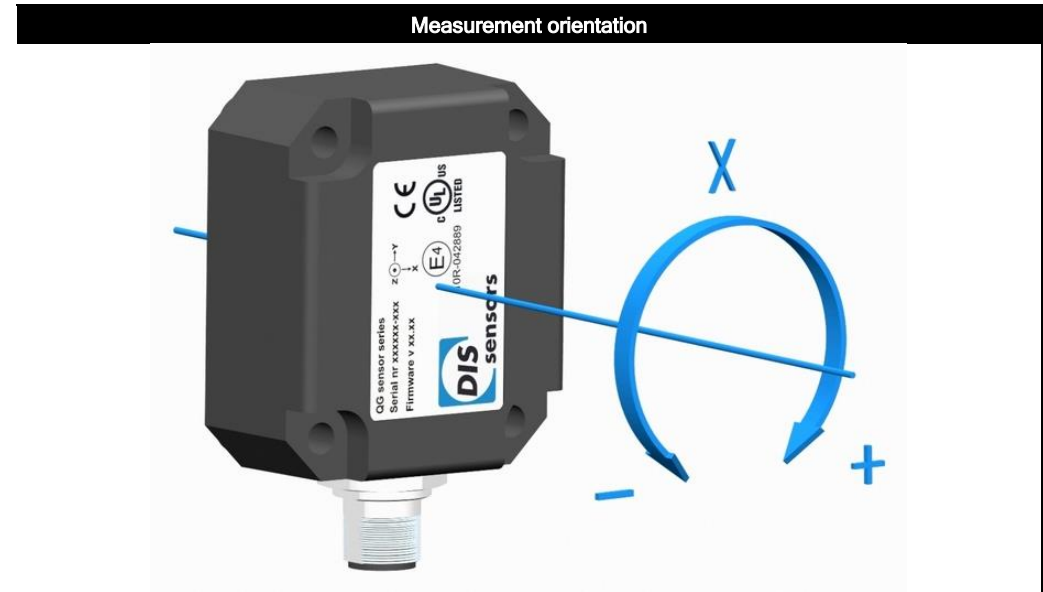
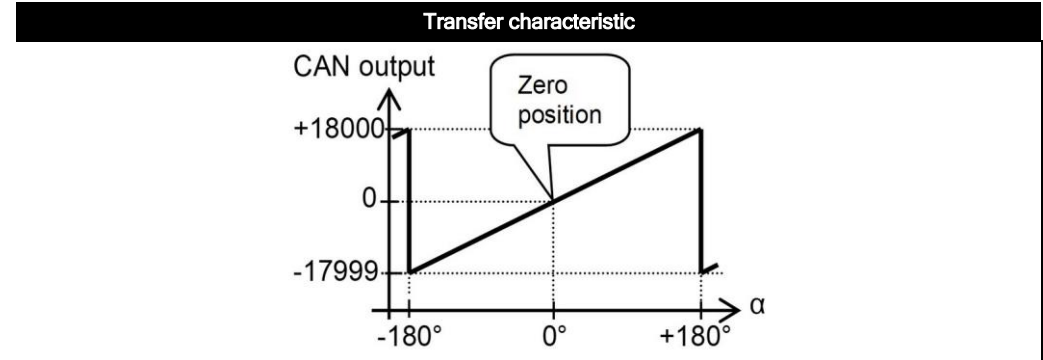
Rotation in vertical plane.

Lateral tilt sensitivity error:
 $< \pm 0,03^\circ/\text{ lateral tilt (typ.)}$
 Max. lateral tilt: 45°

Drawn in the default 0° sensor orientation position
 Zeroing can be done to change the sensor orientation at 0° point

Connection

Wire / pin coding



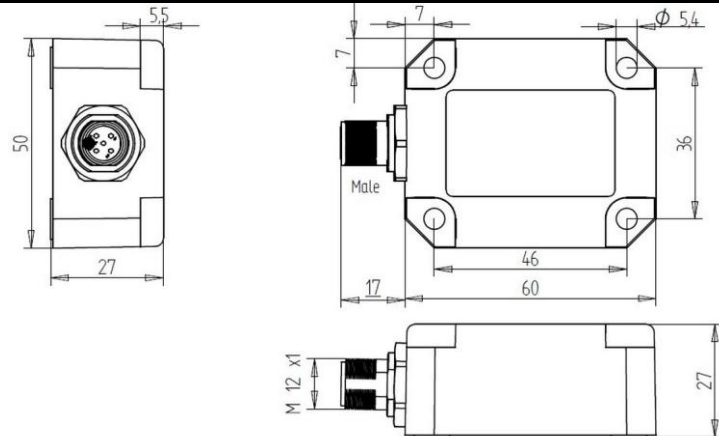
Connectivity (cable length $\pm 10\%$)

Male only or Male & Female (internal T-junction) M12 connector (5 pins, A-coding) (CiA303 V1.8.0) (Brass Nickel coated, contacts copper alloy)

A CANbus always has to be terminated properly according to customers bus topology and general CAN rules.
 The sensor has an on-board internal 120 Ohm CANbus termination resistor that can be switched on by the CANopen dictionary (default: off).
 Alternatively an external M12 termination resistor can be connected when using a Male & Female (internal T-junction) model.
 External M12 termination resistors and T-connectors are available as accessoires, see DIS website.

| | | | |
|--------|---------------|--|--|
| Pin 1: | Shield | | |
| Pin 2: | Vcc | | |
| Pin 3: | Gnd & CAN_GND | | |
| Pin 4: | CAN_H | | |
| Pin 5: | CAN_L | | |

Mechanical dimensions (indicative only)



E4, UL, CAN-manual, EDS-file, Ordering codes

Before using this device, please read this datasheet, the Manual and the Declaration of Conformity carefully (download from dis-sensors.com)

This product is approved for automotive use, approval number: E4-10R-05-4662

Connect this sensor only to an approved CAN controller which must have a grounded shield. Alternatively, connect the sensor housing to a grounded shield. All mentioned EMC standards that are met (see Declaration of Conformity) have been done with the housing connected to a grounded shield.

QG series sensors are intended to measure inclination/acceleration/tilt. Flawless function (acc. spec.) is ensured only when used within specifications. This device is not a safety component acc. to EU Machine Directive (ISO13849). For full redundancy two devices can be used. Modifications or non-approved use will result in loss of warranty and void any claims against the manufacturer.

UL & c-UL listed product (File number E312057, UL508 standards UL60947-5-2 & CSA-C22.2 No. 14)
 Product Identity / Category Code Number (CCN): Industrial Control Equipment / NRKH & NRKH7
 Enclosure rating: type 1, Ambient temperature: max 80 °C (see also datasheet, lowest value applies)
 Electrical ratings: Intended to be used with a Class 2 power source in accordance with UL1310, max. input Voltage 32V dc (see also datasheet, lowest value applies), max. current 200mA
 Accessory Cable Assembly: Any UL-listed (CYJV/7) mating connector with mechanical locking, wire thickness of at least 30 AWG (0,05 mm²), recommended ≤23 AWG (≥0,25 mm²)

(*) Accuracy within spec : approx.. 30sec after boot-up.

(**) Dynamic accuracy figures based on Robot tests, robot performing actions representative for general mobile machine movements

As this device is accelerometer-based the sensor is inherent sensitive for accelerations/vibrations. The majority of these dynamic effects will be eliminated by the on-board gyroscope. The on-board gyroscope and Kalman filtering are special designed to prevent the inclinometer to become significant inaccurate in dynamic situations. The sensor has pre-programmed Kalman algorithms ('Application profiles') that can be selected via the CANbus. Application specific testing must be carried out to check which compensation algorithm fits the application best, and whether this sensor will fulfil customers requirements.

A CAN-manual and EDS-file (CiA306 V1.3.0) can be downloaded from the website (Type H)

Ordering codes:

M12 Male: QG65D-KIXv-360H-CAN-CM-UL, 12609

M12 Male & Female: QG65D-KIXv-360H-CAN-CFM-UL, 12610