

## QG65N2 CANopen Standard accuracy series

QG65N2-KIXv-360-CAN-C(F)M-UL

### Inclination sensor

1 axis vertical mounting

Programmable device

Interface: CANopen

Parameters programmable by DIS configurator and CANopen object dictionary

Measuring range  
 $\pm 180^\circ$



CANopen

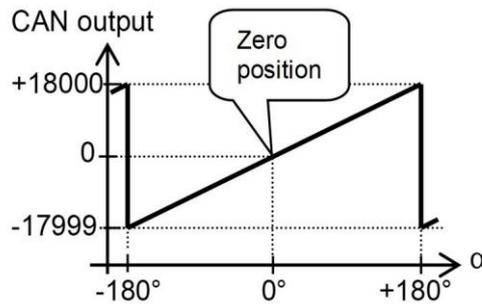


### General specifications 12826, 12829, v20221011

Housing	Reinforced plastic injection molded (Faradex DS, black, EMI shielded by stainless steel fiber in PC)
Dimensions (indicative)	60x50x27 mm
Mounting	Included: 4x M5x25 mm zinc plated steel pozidrive pan head screws, self-tapping (PZ DIN7500CZ) Mounting on flat surface only. Screw crosswise with maximum Torque 2.5 Nm
Ingress Protection (IEC 60529)	IP67, IP69K (with IP69K mating connector)
Relative humidity	0 - 95% (non condensing, housing fully potted)
Weight	approx. 110 gram
Supply voltage	10 - 32 V dc
Polarity protection	Yes
Current consumption	50mA typ. For CFM models (daisy-chained CANbus): max. current internal T-junction: 2.5A
Operating temperature	-40 .. +80 °C
Storage temperature	-40 .. +85 °C
Measuring range	$\pm 180^\circ$
Centering function	Yes (CANout 0 = 0°), range: 360°
Frequency response (-3dB)	0 - 10 Hz
Accuracy (overall @20°C)	0,15° typ.
Offset error	$\pm 0,05^\circ$ typ. ( $\pm 0,1^\circ$ 2 $\sigma$ ) after centering
Non linearity	$\pm 0,1^\circ$ typ., $\pm 0,15^\circ$ 2 $\sigma$ , $\pm 0,2^\circ$ max.
Sensitivity error	not applicable. Repeatability 0,1°
Resolution	0,01°
Temperature coefficient	T>0°C: 0.015°/K typ. en T<0°C: 0.03°/K typ.
Max mechanical shock	10,000g (max 0,2ms)
CAN interface (physical layer)	According to ISO 11898-1 & ISO 11898-2 (CAN 2.0 A/B), Short circuit protected
CANopen application layer and communication profile	CANopen, CiA301 V4.2.0 & EN 50325-4 + Device Profile CiA410 DSP 2.0.0 for inclinometers
Baud rate	250 kbit/s (default, range 10/20/50/100/125/250/500/800/1000 kbit/s
Node Id	01h (range: 01h - 7Fh)
TPDO	For Node ID=01h: TPDO1: 181h, TPDO2: 281h
Event time	TPDO1: 10 - 500 ms (default: 100 ms)
Sync mode	On/off (default: off)
Heartbeat	On/off (default: on, 2s)
Programming options	Baudrate, Node Id, Event time, Sync mode, Heartbeat, Output format, CANbus termination, filtering
Output format	Integer: -17999 to +18000 (PDO1:byte 2,1)
Filtering	Bessel LPF 10Hz on, TPDO averaging off, Output filter off
Modes of operation	Event mode, Sync-mode. Default: auto-startup Event mode
Internal CANbus termination	120 Ohm on/off (default: off)
Boot time	< 0.5 s
Programming options	by optional DIS Configurator and CANopen object dictionary (CAN parameters, filtering)

## QG65N2-KIXv-360-CAN-C(F)M-UL

### Transfer characteristic



CANoutput =  $100 \cdot \alpha$

Zeroing can be done to eliminate mounting offsets.

### Measurement orientation



Rotation in vertical plane.

Lateral tilt sensitivity error:  
 $< \pm 0,03^\circ/\text{lateral tilt (typ.)}$   
 Max. lateral tilt:  $45^\circ$

Drawn in the default  $0^\circ$  sensor orientation position  
 Zeroing can be done to change the sensor orientation at  $0^\circ$  point

### Connectivity (cable length $\pm 10\%$ )

Male only or Male & Female (internal T-junction) M12 connector (5 pins, A-coding) (CiA303 V1.8.0) (Brass Nickel coated, contacts copper alloy)

A CANbus always has to be terminated properly according to customers bus topology and general CAN rules.

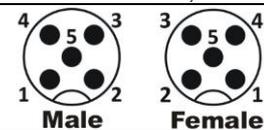
The sensor has an on-board internal 120 Ohm CANbus termination resistor that can be switched on by the CANopen dictionary (default: off).

Alternatively an external M12 termination resistor can be connected when using a Male & Female (internal T-junction) model.

External M12 termination resistors and T-connectors are available as accessories, see DIS website.

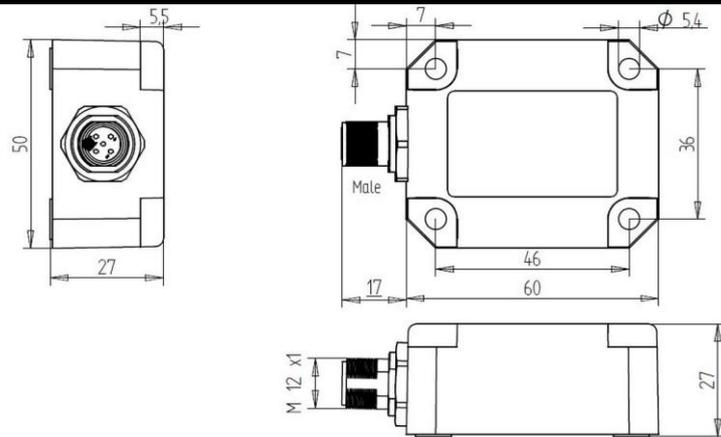
Connection

Pin 1: Shield  
 Pin 2: Vcc  
 Pin 3: Gnd & CAN\_GND  
 Pin 4: CAN\_H  
 Pin 5: CAN\_L



Wire / pin coding

### Mechanical dimensions (indicative only)



### E4ready, UL, CAN-manual, EDS-file, Ordering codes

Before using this device, please read this datasheet, the Manual and the Declaration of Conformity carefully (download from [dis-sensors.com](http://dis-sensors.com))

This product is E4ready and meets Automotive EMC requirements

Connect this sensor only to an approved CAN controller which must have a grounded shield. Alternatively, connect the sensor housing to a grounded shield. All mentioned EMC standards that are met (see Declaration of Conformity) have been done with the housing connected to a grounded shield.

QG series sensors are intended to measure inclination/acceleration/tilt. Flawless function (acc. spec.) is ensured only when used within specifications. This device is not a safety component acc. to EU Machine Directive (ISO13849). For full redundancy two devices can be used. Modifications or non-approved use will result in loss of warranty and void any claims against the manufacturer.

UL & c-UL listed product (File number E312057, UL508 standards UL60947-5-2 & CSA-C22,2 No. 14)  
 Product Identity / Category Code Number (CCN): Industrial Control Equipment / NRKH & NRKH7  
 Enclosure rating: type 1, Ambient temperature: max 80 °C (see also datasheet, lowest value applies)  
 Electrical ratings: Intended to be used with a Class 2 power source in accordance with UL1310, max. input Voltage 32V dc (see also datasheet, lowest value applies), max. current 200mA  
 Accessory Cable Assembly: Any UL-listed (CYJV/7) mating connector with mechanical locking, wire thickness of at least 30 AWG (0,05 mm<sup>2</sup>), recommended ≤23 AWG (≥0,25 mm<sup>2</sup>)

Optional: for accurate mounting two factory mounted positioning pins can be mounted (Ø4mm) replacing 2x M5x25 mm.

As this device is accelerometer-based the sensor is inherent sensitive for accelerations/vibrations.

A CAN-manual can be downloaded from [www.dis-sensors.com](http://www.dis-sensors.com) (Type I)

EDS-file ( CiA306 V1.3.0) can be downloaded from [www.dos-sensors.com](http://www.dos-sensors.com) (Type I)

Ordering codes:

M12 Male: QG65N2-KIXv-360-CAN-CM-UL, 12826

M12 Male & Female: QG65N2-KIXv-360-CAN-CFM-UL, 12829